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7	BRS	L7	10	1 and 6	USPAT	2004/11/2 9 08:40			
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10	BRS	L10	13797	((photo\$5 or picture) same (face or imag\$3) same ((reference or known or stored or database or template\$1 or model\$1 or prestored) near5 (image\$1 or face\$1)))	USPAT	2004/11/2 9 08:42			
11	BRS	L11	91	10 same ((renew\$3 or updat\$3) near10 (reference or database or template\$1 or model\$1 or stored or prestored or known))	USPAT	2004/11/2 9 08:43			
12	BRS	L12	7	1 and 11	USPAT	2004/11/2 9 08:53			

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Nguyen, H.T.; Smeulders, A.W.M.;

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Matthies, L.; Shafer, S.;

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3 Image modeling with position-encoding dynamic trees
Slorkey, A.J.; Williams, C.K.L.;

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4 New methods for dynamic mosaicking
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5 Segmentation of single- or multiple-touching handwritten numeral s using background and foreground analysis

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6 In vivo quantification of a homogeneous brain deformation model for updating preoperative images during surgery

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Rangarajan, A.; Chellappa, R.; Zhou, Y.T.;

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16 Efficient distributed shared state for heterogeneous machine architectures
Chunqiang Tang; Deqing Chen; Dwarkadas, S.; Scott, M.L.;

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22 **A weighted distance approach to relevance feedback**

Aksoy, S.; Haralick, R.M.; Cheikh, F.A.; Gabbouj, M.;

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24 **Obstacle detection and self-localization without camera calibration using projective invariants**

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27 **Two-dimensional recursive estimation for ARMA signal models**
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Trebossen, H.; Rudant , J.P.; Classeau, N.; Fruneau, B.; Courel, M.F.; Trouve, Deffontaines, B.; Mvogo, J.; Onana, V.;

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